

SPINNING FINE SUN SENSOR
Typical Model



CONFIGURATION

- REDUNDANT SYSTEM: 2 Sensors
(with redundant electronics)
- NO. OF MEASUREMENT AXES: 1 plus sun pulse
(each sensor)

PARAMETERS

- FIELD OF VIEW: $\pm 64^\circ$ Fan-shaped (each sensor).
- ACCURACY: Sun Pulse: $\pm 0.1^\circ$ at 0°
 $\pm 0.3^\circ$ at 40°
 $\pm 0.6^\circ$ at 64°
Aspect Angle: $\pm 0.1^\circ$ 0° to 40°
 $\pm 0.25^\circ$ 40° to 64°
- RESOLUTION: Coarse Angle: 1°
Fine Angle: $< 0.015^\circ$ (limited only
by spacecraft A/D converter).
- INPUT POWER: $28 \pm 7 V_{DC}$ (other ranges available)
(Typical power dissipation 0.4 W).
- OUTPUT: - Sun Pulse (one per revolution)
- Parallel Coarse Data
- Fine Data (V_{SINE} , V_{COSINE} , V_{BIAS})
- WEIGHT
Sensor: 0.24 lb (109 g) nominal
Electronics¹: 1.05 lb to 1.6 lb (477 g to 726 g)
- SIZE
Sensor²: 2.6"×1.3"×1.0" (66×33×25 mm)
Electronics²: 2.0"×3.2"×3.5" (51×82×89 mm)

HERITAGE

ERG, BSAT-2, IMAGE, INDOSTAR,
KOREASAT, INMARSAT, GPS IIR,
GGs, AURORA, GEOTAIL, DBS, MS-
T5, VIKING, SAN MARCOS,
SCATHA, ISEE-C, TELSAT, BSE,
SATCOM.

APPLICATIONS

- Attitude Determination of Spinning
Spacecraft
- Sun Acquisition
- Fail-Safe Recovery

NOTES

1. Depending on processing and power.
2. Exclusive of connectors.